

RAÍCES ECUACIONES NO LINEALES

(1)

$$f(x) = 0$$

Bisección

$$a \rightarrow b$$

$$c = \frac{a+b}{2}$$

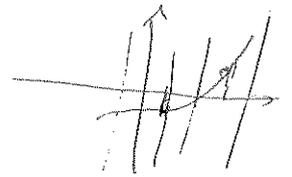
$$f(a) \cdot f(c) > 0 \rightarrow b = c$$

$$f(a) \cdot f(c) < 0 \rightarrow a = c$$

$$\left. \begin{matrix} \dots \\ \dots \end{matrix} \right\} |a-b| < \epsilon$$

$$|b-a| < \epsilon_{rel} \cdot \text{MAX} \left(\frac{a+b}{2}, |b-a|_0 \right)$$

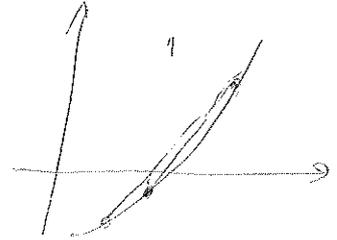
$$\frac{|b-a|}{|a|} = \epsilon_{rel}$$



Regula falsi

$$c = \frac{a f(b) - b f(a)}{f(b) - f(a)}$$

→ + horquillado



Secante: $x_{i+1} =$

Müller

$$x_0, x_1, x_2$$

$$\hookrightarrow p(x) = a(x-x_2)^2 + b(x-x_2) + c$$

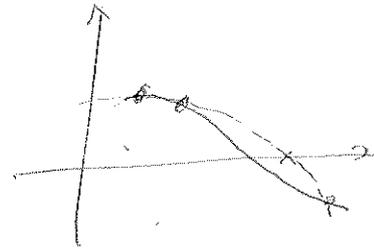
$$a = \frac{(x_1-x_2)[f(x_0)-f(x_2)] - (x_0-x_2)[f(x_1)-f(x_2)]}{(x_0-x_2)(x_1-x_2)(x_0-x_1)}$$

$$b = \frac{(x_0-x_2)^2[f(x_1)-f(x_2)] - (x_1-x_2)^2[f(x_0)-f(x_2)]}{(x_0-x_2)(x_1-x_2)(x_0-x_1)}$$

$$c = f(x_2)$$

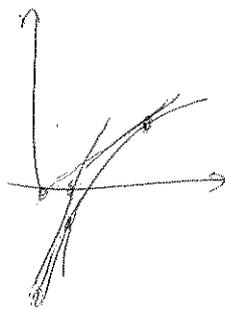
$$\hookrightarrow x_0 \leftarrow x_1, x_1 \leftarrow x_2, x_2 \leftarrow x_3$$

$$x_3 = x_2 + \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \Rightarrow \text{menor } | |$$



Newton-Raphson

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$



PROBLEMAS LINEALES

LU

$$c_{ij} = a_{ij} - \sum_{k=1}^{i-1} b_{ik} c_{kj} \quad i \leq j$$

$$b_{ij} = \frac{a_{ij} - \sum_{k=1}^{j-1} b_{ik} c_{kj}}{c_{jj}} \quad i > j$$

$$B \cdot C = A$$

pivote = $\text{MAX} \{ |c_{jj}|, |b'_{j+1j}|, \dots, |b'_{njj}| \}$ fila $j' \times k(\rightarrow)$
 $b'_{ij} = a_{ij} - \sum_{k=1}^{j-1} b_{ik} c_{kj}$
 + guardar permutaciones $i \rightarrow (3, 1, 2) \rightarrow P = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$ $PA = LU$

Determinante

$$|A| = (-1)^{\# \text{permutas}} \cdot \prod_{k=1}^N c_{kk}$$

Sistema ecuas lineales

$$A \cdot \vec{x} = \vec{w} \rightarrow P^{-1} L U \cdot \vec{x} = \vec{w}$$

$$L \cdot U \cdot \vec{x} = P \cdot \vec{w}$$

$$y_i = w_i - \sum_{j=1}^{i-1} b_{ij} y_j \quad \text{x orden, recurrente}$$

$$x_i = \frac{y_i - \sum_{j=i+1}^N c_{ij} x_j}{c_{ii}} \quad \text{orden inverso}$$

Inversión matriz

$$A^{-1} = U^{-1} L^{-1} P$$

$$U^{-1} \rightarrow e_{jj} = \frac{1}{c_{jj}}, \quad e_{ij} = - \frac{\sum_{k=1}^{j-1} l_{ik} c_{kj}}{c_{jj}} \quad j > i$$

$$L^{-1} \rightarrow d_{ij} = - \frac{b_{ij}}{c_{jj}} - \sum_{k=1}^{i-1} b_{ik} d_{kj} \quad \text{for } i > j$$

Descomposición Cholesky

Matrices simétricas + positivas

$$A = L \cdot L^T$$

L triangular inferior $d_{ii} = l_{ii}^2$

$$l_{ii} = \left[a_{ii} - \sum_{k=1}^{i-1} l_{ik}^2 \right]^{1/2}$$

$$l_{ji} = \frac{1}{l_{ii}} \left[a_{ji} - \sum_{k=1}^{i-1} l_{jk} l_{ik} \right] \quad j > i$$

$$l_{11} = \sqrt{a_{11}}$$

$$l_{21} = \frac{a_{21}}{l_{11}}$$

$$l_{31} = \frac{a_{31}}{l_{11}}$$

$$l_{22} = \sqrt{a_{22} - l_{21}^2}$$

$$l_{32} = \frac{1}{l_{22}} (a_{32} - l_{31} l_{21})$$

$$l_{33} = \sqrt{a_{33} - l_{31}^2 - l_{32}^2}$$

Método Jacobi

Matrices simétricas $A = A^T$

$$A \rightarrow R_1^T \overbrace{A}^{A'} R_1 \rightarrow R_2^T R_1^T A R_1 R_2 \rightarrow \dots$$

$$R_{pq} = \begin{pmatrix} 1 & & & \\ & \cos \theta & \sin \theta & \\ & -\sin \theta & \cos \theta & \\ & & & \ddots \end{pmatrix} \quad \begin{aligned} R_{pp} &= \cos \theta = R_{qq} \\ R_{pq} &= \sin \theta = -R_{qp} \\ R_{ii} &= 1 \quad i \neq p, q \\ \text{resto} &= 0 \end{aligned}$$

Eliminas a_{pq} !!

$$\hookrightarrow \tan 2\theta = - \frac{2a_{pq}}{(a_{pp} - a_{qq})} \longrightarrow A' = R^T A R$$

$$a'_{pq} = 0$$

$$a'_{ip} = a_{ip} \cos \theta - a_{iq} \sin \theta \quad i \neq p, q$$

$$a'_{iq} = a_{ip} \sin \theta + a_{iq} \cos \theta \quad i \neq p, q$$

$$a'_{pp} = \frac{1}{2} (a_{pp} \cos^2 \theta + a_{qq} \sin^2 \theta - 2a_{pq} \sin \theta \cos \theta)$$

$$a'_{qq} = a_{pp} \sin^2 \theta + a_{qq} \cos^2 \theta + 2a_{pq} \sin \theta \cos \theta$$

LU
3x3

$$c_{11} = a_{11}$$

$$c_{12} = a_{12}$$

$$c_{13} = a_{13}$$

$$b_{21} = \frac{a_{21}}{c_{11}}$$

$$c_{22} = a_{22} - b_{21} c_{12}$$

$$c_{23} = a_{23} - b_{21} c_{13}$$

$$b_{31} = \frac{a_{31}}{c_{11}}$$

$$b_{32} = \frac{a_{32} - b_{31} c_{12}}{c_{22}}$$

$$c_{33} = a_{33} - b_{31} c_{13} - b_{32} c_{23}$$

$$y_1 = w_1$$

$$x_3 = y_3 / c_{33}$$

$$y_2 = w_2 - b_{21} y_1$$

$$x_2 = \frac{y_2 - c_{23} x_3}{c_{22}}$$

$$y_3 = w_3 - b_{31} y_1 - b_{32} y_2$$

$$x_1 = \frac{y_1 - c_{12} x_2 - c_{13} x_3}{c_{11}}$$

INTERPOLACIÓN

Polinomio interpolador

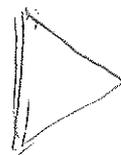
$$\xi(x) = \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \cdot \prod_{i=0}^n (x-x_i) \quad \text{orden } n$$

Lagrange

$$P_n(x) = \sum_{k=0}^n \prod_{i=0, i \neq k}^n \frac{x-x_i}{x_k-x_i} y_k \quad L_k(x_i) = \delta_{ik} \quad i=1, \dots, n$$

Diferencias divididas

$$\begin{aligned} f[x_i] &= f(x_i) \\ \frac{f[x_{i+1}] - f[x_i]}{x_{i+1} - x_i} &= f[x_i, x_{i+1}] \end{aligned}$$



$$f[x_i, \dots, x_{i+k}] = \frac{f[x_{i+1}, \dots, x_{i+k}] - f[x_i, \dots, x_{i+k-1}]}{x_{i+k} - x_i}$$

$$P_n(x) = \frac{f[x_0]}{1} + \sum_{k=1}^n f[x_0, \dots, x_k] \cdot \prod_{i=0}^{k-1} (x-x_i) = f[x_0] + f[x_0, x_1](x-x_0) + f[x_0, x_1, x_2](x-x_0)(x-x_1) + \dots$$

Newton

$$P_{i+1}(x) = \frac{(x-x_i)P_i(x) - (x-x_{i+1})P_i(x_{i+1})}{x_{i+1} - x_i} \quad P_0 = f_0$$

Estimación error

$$\epsilon = \text{MAX} \{ |P_{0123} - P_{012}|, |P_{0123} - P_{123}| \}$$



Chebyshev

$$T_n(x) = \cos(n \arccos(x)) \quad x \in [-1, 1] \rightarrow x' = \frac{b-a}{2}x + \frac{b+a}{2}$$

$$x = \cos\left(\frac{2k+1}{2n}\pi\right) \quad n \rightarrow n^{\circ} \text{ puntos}$$

$$T_{n+1} = 2xT_n(x) - T_{n-1}(x) \quad \begin{aligned} T_0(x) &= 1 \\ T_1(x) &= x \end{aligned}$$

Splines

ubicos: $S_j = a_j + b_j(x-x_j) + c_j(x-x_j)^2 + d_j(x-x_j)^3$

$$a_j = y_j$$

- $S(x_j) = y_j$
- $S_{j+1}(x_{j+1}) = S_j(x_{j+1})$
- $S'_{j+1}(x_{j+1}) = S'_j(x_{j+1})$
- $S''_{j+1}(x_{j+1}) = S''_j(x_{j+1})$

splines naturales

$$S''_0(x_0) = S''_{n-1}(x_n) = 0$$

sujetos

$$S'_0(x_0) = f'(x_0); S'_n(x_n) = f'(x_n)$$

$$\begin{pmatrix} 1 & 0 & \dots & 0 \\ h_0 & 2(h_0+h_1) & h_1 & \dots \\ 0 & h_1 & 2(h_1+h_2) & h_2 \\ \dots & \dots & \dots & \dots \\ 0 & \dots & \dots & 1 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{3}{h_1}(k_2 - a_1) - \frac{3}{h_0}(k_1 - a_0) \\ \frac{3}{h_2}(k_3 - a_2) - \frac{3}{h_1}(k_2 - a_1) \\ \dots \\ 0 \end{pmatrix}$$

libre $\rightarrow S''_0(x_0) = S''_n(x_n) = 0$

sujeta $\rightarrow S''(x_0) = f''(x_0); S'(x_0) = f'(x_0)$

$$d_j = \frac{c_{j+1} - c_j}{3h_j}$$

$$b_j = \frac{a_{j+1} - a_j}{h_j} - \frac{h_j}{3}(2c_j + c_{j+1})$$

impuntos ordenados

DERIVACIÓN E INTEGRACIÓN NUMÉRICA

Derivadas

$$f'(x) \approx \frac{f(x+h) - f(x)}{h} - \frac{f''(\xi)h}{2!}$$

$$f'(x) = \frac{1}{2h} (f(x+h) - f(x-h)) - \frac{h^2}{6!} f'''(\xi) \leftarrow$$

$$f''(x) = \frac{1}{h^2} [f(x+h) + f(x-h) - 2f(x)] - \frac{h^2}{12} f^{(4)}(\xi)$$

Richardson

$$D = d_0(h) + a_2 h^2 + a_4 h^4 + \dots = d_0\left(\frac{h}{2}\right) + \frac{a_2}{4} h^2 + \dots$$

$$= \frac{4d_0\left(\frac{h}{2}\right) - d_0(h)}{3} - \frac{a_4 h^4}{4} + \dots$$

2ⁿ intervalos

$$D(n, k) = \frac{4^k D(n, k-1) - D(n-1, k-1)}{4^k - 1}$$

\downarrow \downarrow
 2ⁿ orden
 int. Extrap.
 >

Integrales:

$$\int_a^b f(x) dx \approx h \sum_{k=0}^n \alpha_k f(x_k) \quad \alpha_k = \int_0^1 \phi_k(s) ds \quad \phi_k(s) = \frac{h}{\pi} \left(\frac{s-i}{k-i} \right)$$

Trapezoidal

$$\frac{h}{2} (f_0 + f_n) \quad e = \frac{h^3}{12} f''(\xi) \quad \text{repetido} \rightarrow \frac{h}{2} [f_0 + f_n] + h \sum_{i=1}^{n-1} f_i$$

$$R(n) = \frac{R(n-1)}{2} + h \sum_{k=1}^{2^{n-1}} f(a + (2k-1)h) \quad , \quad R(b) = (f(a) + f(b)) \frac{(b-a)}{2}$$

$$|R(n) - R(n-1)| < \epsilon \quad e = \frac{b-a}{12} h^2 f''(\xi)$$

Simpson

(3/8) Bode

$$\int_a^b f(x) dx = \frac{h}{3} (f_0 + 4f_1 + f_2) - \frac{h^5}{90} f^{(4)}(\xi)$$

$$\text{↳ Repetido: } = \frac{h}{3} \left(f_0 + f_n + 4 \sum_{i=1}^{n/2} f(x_{2i-1}) + 2 \sum_{i=2}^{n/2} f(x_{2i-2}) \right) - \frac{1}{180} (b-a) h^4 f^{(4)}(\xi)$$

Romberg

$$I \approx R(n, 0) + c_2 h^2 + c_4 h^4 + \dots$$

2ⁿ intervalos → extrapolado Richardson

$$R(n, m) = \frac{4^m R(n, m-1) - R(n-1, m-1)}{4^m - 1}$$

MODELADO DE DATOS EXPERIMENTALES

$$\chi^2 = \sum_{i=1}^n \frac{1}{\sigma_i^2} [y_i - f(x_i; p_1, \dots, p_m)]^2 \rightarrow \frac{\partial \chi^2}{\partial p_k} \text{ m\u00ednimo}$$

$$\{x_i, y_i, \sigma_i\}_{i=1}^n \rightarrow f(x_i; \vec{p}) \mid \vec{p} = \{p_1, \dots, p_m\} \rightarrow \text{PMV}$$

Lineales en par\u00e1metros

$$f(x; \vec{p}) = \sum_{j=1}^m p_j f_j(x)$$

$$\rightarrow \underset{m \times m}{F} \cdot \underset{m}{\vec{p}} = \underset{m}{\vec{v}}$$

$$F_{kj} = F_{jk} = \sum_{i=1}^n \frac{f_k(x_i) f_j(x_i)}{\sigma_i^2}$$

$$v_k = \sum_{i=1}^n \frac{y_i f_k(x_i)}{\sigma_i^2}$$

$$F^{-1} = C \equiv \text{matriz covarianza} \rightarrow \sigma^2(p_j) = C_{jj}$$

- F
- v
- $p_j = \sum C_{jk} \theta_k$
- $\sigma(p_j) = \sqrt{C_{jj}}$
- χ^2

Recta

$$p_1 + p_2 x \rightarrow p_1 = \frac{1}{|F|} \left\{ \sum \frac{x_i^2}{\sigma_i^2} \sum \frac{y_i}{\sigma_i^2} - \sum \frac{x_i}{\sigma_i^2} \sum \frac{x_i y_i}{\sigma_i^2} \right\}$$

$$p_2 = \frac{1}{|F|} \left\{ \sum \frac{1}{\sigma_i^2} \sum \frac{x_i y_i}{\sigma_i^2} - \sum \frac{x_i}{\sigma_i^2} \sum \frac{y_i}{\sigma_i^2} \right\}$$

Calidad ajustes

$\{x_i, y_i, \sigma_i\} \rightarrow N$ experimentos $\rightarrow N \times n$ puntos $\rightarrow N$ ajustes

$N \times m$ - p\u00e1metros $\{p_1, \dots, p_m\}$

$N \chi^2$

$$\chi^2 = \sum \frac{(y_i - f_i)^2}{\sigma_i^2} \approx \nu = n - m$$

$\rightarrow \text{Exp.} \rightarrow \chi_0^2 \approx \nu$

1) Si $\chi_0^2 / \nu - 2\sqrt{2/\nu} \leq \chi_0^2 \leq \nu + \sqrt{2/\nu}$ ✓

2) $\chi_0^2 \ll \nu \Rightarrow \frac{\chi_0^2}{\nu} \ll 1 \rightarrow$ errores muy grandes

3) $\chi_0^2 \gg \nu \Rightarrow \frac{\chi_0^2}{\nu} \gg 1 \rightarrow$ cualquier funci\u00f3n pasa

a) Medidas incorrectas \rightarrow repetir

b) Errores muy peque\u00f1os \rightarrow buscar

c) Funci\u00f3n modelo inadecuada \rightarrow replantear teor\u00eda

Probabilidad χ^2

$$P(\chi^2 \gg \chi_0^2) = \int_{\chi_0^2}^{\infty} f(\chi^2) d\chi^2 = 1 - \int_{-\infty}^{\chi_0^2} f(\chi^2) d\chi^2$$

1) $0,05 \leq P(\chi^2 > \chi_0^2) \leq 0,95$

2) $P(\chi^2 > \chi_0^2) \geq 95\%$

3) $P(\chi_0^2) \leq 5\%$

$\ll 1\% \rightarrow \text{MAL}$

Ecuaciones Diferenciales Ordinarias

$$\frac{dy}{dt} = F(t, y), \quad y(t_0) = y_0$$

Método de Euler:

$$\vec{y}(t+h) \approx \vec{y}(t) + h \cdot \vec{F}(t, \vec{y}) \rightarrow y_{n+1} = y_n + h \cdot \frac{dy_n}{dt}$$

Método punto medio:

$$\vec{y}(t+h) \approx \vec{y}(t-h) + 2h \vec{F}(t, \vec{y}(t)) \rightarrow y_{n+1} = y_{n-1} + 2h \vec{F}(t_n, y_n)$$

1er paso → Euler

Método predictor-corrector

$$y(t+h) = y(t) + \frac{1}{2}h [F(t, y(t)) + F(t+h, y(t+h))]$$

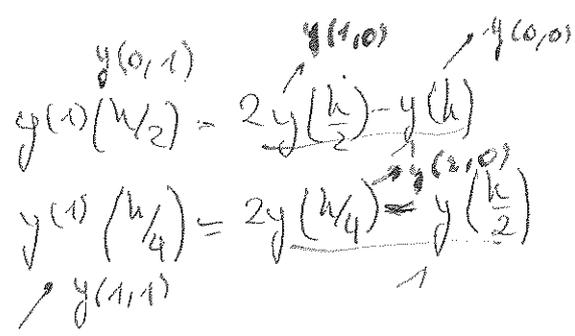
$$y_{n+1} = y_n + \frac{1}{2}h (F(t_n, y_n) + F(t_{n+1}, y_{n+1}^*)) \rightarrow \text{1er paso } y^* \text{ Euler}$$

Cálculo reglas integración

P. medio Euler → extrapolar

$$y(b) = y(a) + h_1(b)h + h_2(b)h^2 + O(h^3)$$

$$\hookrightarrow y(b) = \frac{4y^{(1)}(h/4) - y^{(1)}(h/2)}{3}$$



$$\Rightarrow y(n, m) = \frac{2^m y(n, m-1) - y(n-1, m-1)}{2^m - 1}$$

Métodos de Runge-Kutta

Orden 2:

$$y(t+h) = y(t) + hF(t, y) (\omega_1 + \omega_2) + \alpha \omega_2 h^2 \frac{\partial F}{\partial t} + \beta \omega_2 h^2 \frac{\partial F}{\partial y}$$

$\omega_1 + \omega_2 = 1$
 $\alpha \omega_2 = 1/2$
 $\beta \omega_2 = 1/2$

→ $\omega_1 = \omega_2 = 1/2, \alpha = \beta = 1 \Rightarrow$ Predictor-corrector
 → $\omega_1 = 0, \omega_2 = 1, \alpha = \beta = 1/2 \Rightarrow$ Punto medio

Orden 4: → solo 1 combinación

$$y(t+h) = y(t) + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4) + O(h^5)$$

$$\begin{cases} k_1 = h F(t, y) \\ k_2 = h F(t + \frac{h}{2}, y + \frac{k_1}{2}) \\ k_3 = h F(t + \frac{h}{2}, y + \frac{k_2}{2}) \\ k_4 = h F(t + h, y + k_3) \end{cases}$$

General

$$y(t+h) = y(t) + \phi(t, y) / \phi(t, y) = \sum \alpha_j k_j$$

$$k_m = h F(t + a_m h, y + b_{m1} k_1 + b_{m2} k_2 + \dots + b_{m, m-1} k_{m-1})$$

Algoritmo de Butcher-Stoer

$$y(t+h) = \frac{1}{2} [f_j + f_{j-1} + h F(t+h, f_j)]$$

$$h = \frac{H}{j}$$

$$\begin{cases} f_0 = y(t) = y_0 \text{ 1o Euler} \\ f_{l+1} = f_{l-1} + 2h F(t+l, f_l) \end{cases}$$

$$\hookrightarrow y(t+h) = \frac{4^m y_j^{(m)} - y_j}{4^m - 1} \quad \leftarrow \text{si } j_i \text{ pares}$$